ELECTRO-PNEUMATIC POSITIONER

Linear & Rotary Type

A Solid Workhorse You Can Depend On For Consistent, Reliable Control

Power-Genex Electro-Pnuematic Positioners (4-20mA linear and rotary type) are advanced control devices which provide unparalleled stability in difficult environments

FEATURES

- Easy Maintenance
- ♦ Precise Calibration with simple SPAN and ZERO adjustments
- Simple Conversion to Direct Acting or Reverse Acting
- ♦ 1/2 Spilt Range Available by simple adjustments without changing parts
- Simple Structure for feedback connection
- Corrosion-Resistant Aluminium Diecast Body
- Sensitive and Correct Response for high performance
- Economical Energy Saving
- Extremely Vibration Resistant Design
- Stainless Steel Gauges Standard
- A Restricted Pilot Valve Orifice Kit for small actuators included
- Optional Built-in Limit Switches or 4-20mA Position Transmitter for feedback
- Optional Directly-Mountable Positioner guaranteeing more outstanding stability



EPL (Linear Type)

SPECIFICATIONS

Туре	EPL		EPR	
	Linear Type (le	ver feedback)	Rotary Type (d	cam feedback)
Item	Single	Double	Single	Double
Input Signal	420mA DC (Note.1)			
Input Resistance	235 ± 15 ohms			
Supply Air Pressure	Max. 7.0 kgf/cm ² (100psi)			
Standard Stroke	10 ~ 80mm(Note.2)		60 ~ 100° (Note.3)	
Air Piping Connection	PT 1/4 (NPT 1/4)			
Conduit Connection	PF 1/2 (NPT 1/2)			
ExplosionProof Classification	Exmd BT6, Exmd C(H ₂)T6, IP66, Exia BT6			
Ambient Temperature	-20 ~ 70 °C			
Pressure Gauge	Stainless Steel			
Output Characteristics	Linear			
Linearity	Within ± 1.	.0 % F.S.	Within ±	1.5 % F.S.
Sensitivity	Within ().1 % F.S.	Within	0.5 % F.S.
Hysteresis	Within (0.5 % F.S.	Within	1.0 % F.S.
Repeatability	Within ± 0.5 % F.S.			
Air Consumption	5 LPM (Sup. 1.4 kgf/cm²)			
Flow Capacity	80 LPM (Sup. 1.4 kgf/cm²)			
Material	Aluminium Diecast Body			
Weight	2.9 kg (with a terminal box)			



EPR (Rotary Type)

- Note: 1) 1/2 spilt range can be adjusted
 - 2) Feedback lever for stoke 80° ~150mm is available (EPL) 3) Stroke can be adjusted to 0° ~ 60° or 0° ~ 100° (EPR)

PRINCIPLES OF OPERATION

EPL (Linear Operation)

As the signal current from the controller increases, the plate spring of the torque motor works as a pivot. As the armature receives the rotary torque in the counter-clockwise direction, the counter-weight is pushed to the left, the clearance between the nozzle and the flapper will increase, and the nozzle back pressure will decrease. As a result, the exhaust valve of the pilot valve moves to the right, and the output pressure of OUT1 increases to move the actuator diaphragm.

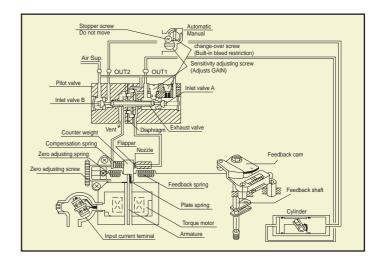
The valve stem goes up or down by the movement of the actuator diaphragm, and the feedback spring lengthens or shortens by the movement of the feedback lever. The valve stem stays in the position where the spring force is balanced with the force generated by the input current in the torque motor. The compensation spring is for direct feedback of the motion of the exhaust valve and is connected to the counter weight to enhance the stability of the loop. The zero point is adjusted by changing the zero adjustment spring tension.

nsation spring Transmission pin Zero adjusting spring Lock screw Transmission leve Torque motor

EPR (Rotary Operation)

As the signal current from the controller increases, the plate spring of the torque motor works as a pivot. As the armature receives the rotary torque in the counter-clockwise direction, the counter-weight is pushed to the left, the clearance between the nozzle and the flapper will increase, and the nozzle back pressure will decrease. As a result, the exhaust valve of the pilot valve moves to the right, and the output pressure of OUT1 increases (as OUT 2 decreases) to move the cylinder actuator.

The movement of the actuator in turn rotates the feedback shaft, and the feedback spring lengthens or shortens by the movement of the feedback cam connected to the feedback shaft. The actuator stays in the position where the spring force is balanced with the force generated by the input current in the torque motor. The compensation spring is for direct feedback of the motion of the exhaust valve and is connected to the counter weight to enhance the stability of the loop. The zero point is adjusted by changing the zero adjustment spring tension.



nlet valve A

Actuator diaphragm

Stopper scre

INSTALLATION

EPL (Linear Type)

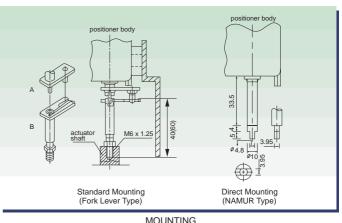
- 1) Connect the feedback lever to the control valve stem at position where the angle between the valve stem and the feedback lever is 90 degrees as shown to the right when the input signal is set to 12mA(50%).
- 2) The stroke range for the best performance should be 10 ~80mm and the operation angle of the feedback lever should be between Min. 10 degrees and Max. 30 degrees to carry out accuracy and linearity perfectly.

elimination spring 50% position 100% (or 0%)

FEEDBACK LEVER INSTALLATION

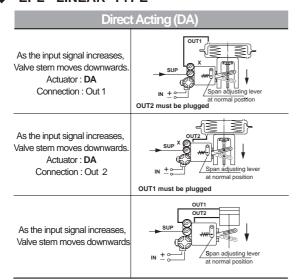
EPR (Rotary Type)

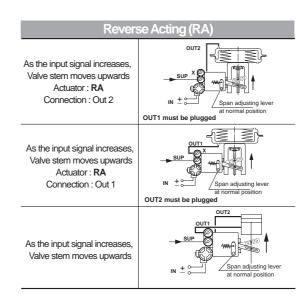
Mount the positioner to the actuator at position where the feedback lever is in perfect alignment with the rotary actuator output shaft. The spring pin of the feedback lever "A" should be placed in the orifice of the feedback lever "B". Be sure that linearity and hysteresis will suffer if these alignment and placement are not correct.



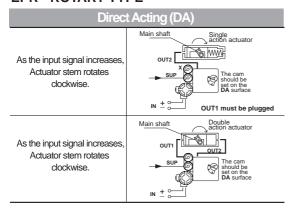
AIR PIPING

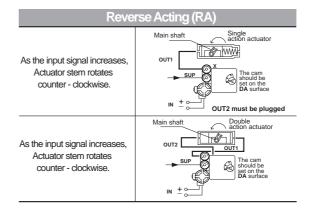
◆ EPL - LINEAR TYPE





♦ EPR - ROTARY TYPE





HOW TO ORDER



Actuator Operation Input Signal Feedback Lever Type Pressure Gauge (SUP. OUT)

Construction

Pilot Valve Orifice

Position Feedback

Mounting Type

Description	Code
Actuator Operation:	
- Linear Type	L
- Rotary Type	R
Input Signal:	
420mA	1
Feedback Lever Type:	
- Linear Type	A : Stroke (10~80mm)
	B : Stroke (80~150mm)
- Rotary Type	A: M6 x 40L (standard)
	B : M8 x 40L
	C : M6 x 60L
	D : M8 x 60L
Pressure Gauge:	1:4 kgf/cm²(60psi)
	2:6 kgf/cm²(80psi)
	3:10 kgf/cm²(150psi)

Description	Code
Construction	N: Without a Terminal Box
	W: With a Terminal Box (standard)
Pilot Valve Orifice	S: Standard Actuator (Actuator Volume over 180 cm³) M: Small Actuator (Actuator Volume 90 ~ 180 cm³)
Position Feedback	N:None(standard) O: Position Transmitter (Output Signal 420mA) L: 2 SPDT Limit Switches (only for EPR)
Mounting Type (only for EPR)	F: Standard Mounting (Fork Lever Type) D: Direct Mounting (NAMUR Type)

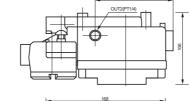
Example

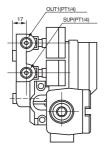
EPR-1A2WSOF

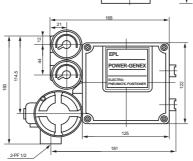
E/P Rotary Type Positioner with Input Signal 4...20mA , Feedback Lever M6 x 40L , Pressure Gauge 6 kgf/cm², Terminal Box , Pilot Valve Orifice for Standard Actuator , Position Transmitter (Output Signal 4...20mA), Standard Mounting (Fork Lever Type)

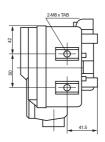
DIMENSIONS

◆ EPL - LINEAR TYPE

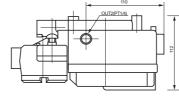


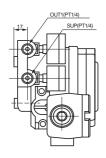


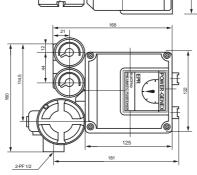


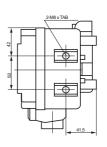


EPR - ROTARY TYPE



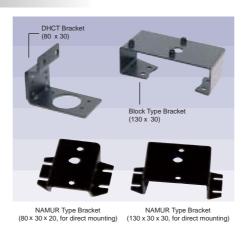


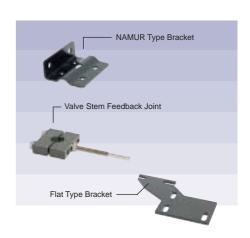




ACCESSORIES







Position Transmitter Kit

Rotary Type Mounting Brackets

Linear Type Mounting Brackets





DAEHAN CONTROL TECH CO., LTD.

RM 503, DAERYUNG TECHNO TOWN II , 569-21, GASANDONG, GEUMCHUNGU, SEOUL, 153-023 KOREA

TEL: +82-2-863-4015 http://www.power-genex.com FAX: +82-2-863-4019 dhctl@chollian.net